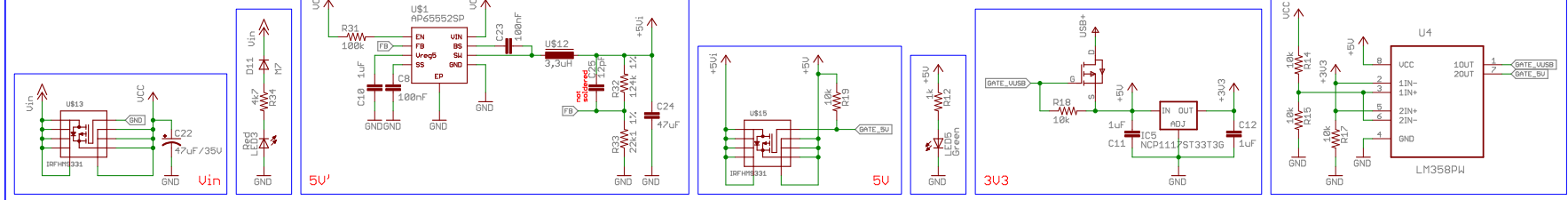
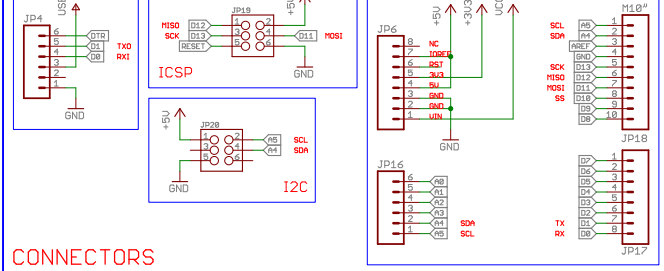


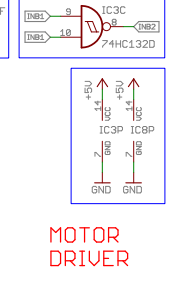
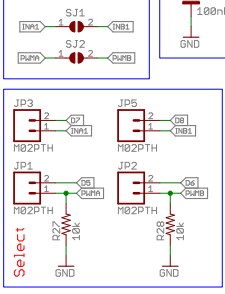
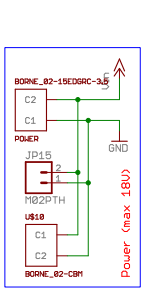
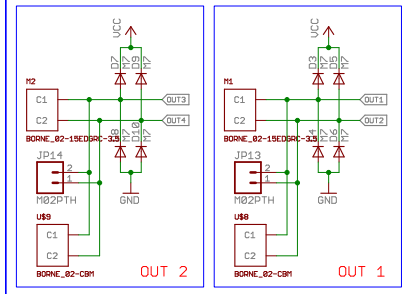
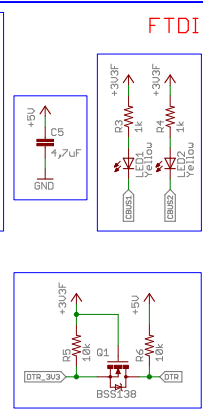
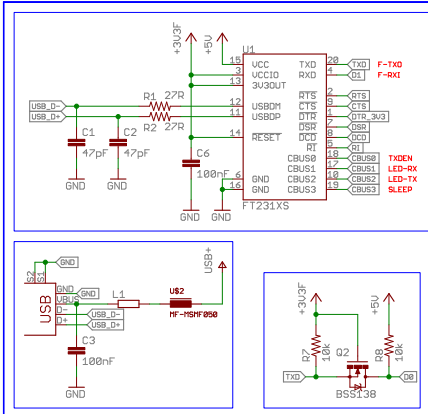
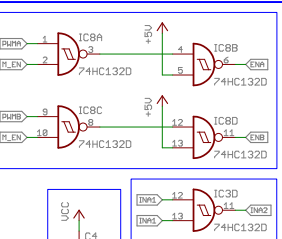
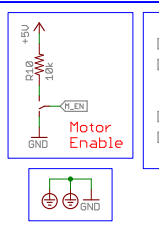
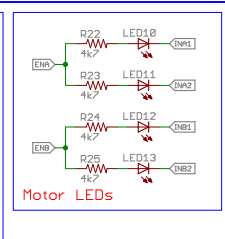
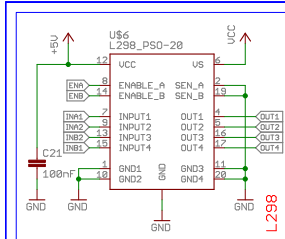
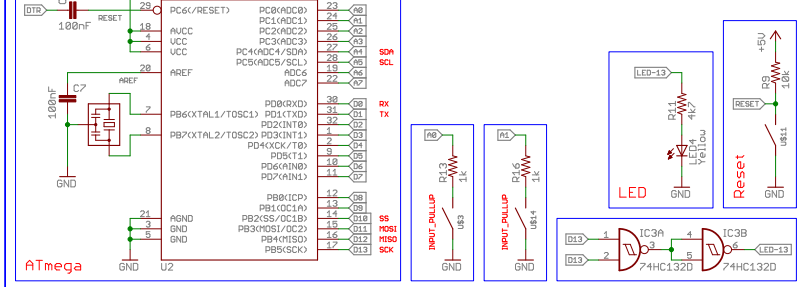
# POWER



# CONNECTORS

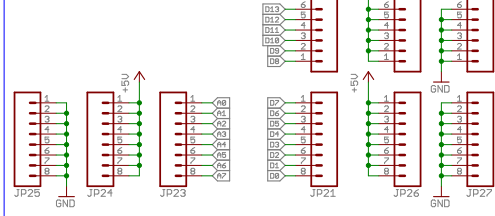


# ATMEGA



NOTE: the ferrite bead (WE-CBF 0805) was tested and isn't necessary. However, it prevented a voltage drop of about 20 mV in the power supply, so it is best to be replaced by a 0 ohm resistor in case it might be useful.

# PINS



RoboCore  
Julieta v1.0  
22/05/16

Released under the Creative Commons Attribution Share-Alike 4.0 license.  
<https://creativecommons.org/licenses/by-sa/4.0/>  
Design by: Original design by Arduino team (Arduino Uno and 2009);  
BlackBoard by RoboCore;  
Motor Driver 2x2A by RoboCore;  
Julieta by RoboCore.